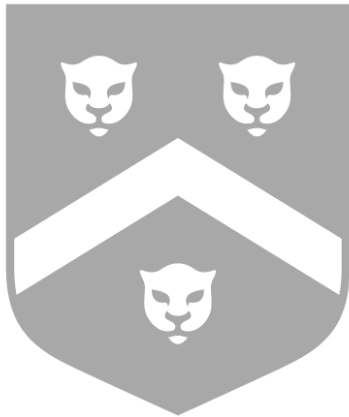


Binary Search Trees and Priority Queues



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Binary Search Trees

Binary Search Trees

Example

Searching

Search Example

Interface

UML Diagram

find()

add()

add()

Priority Queues

Binary Search Trees

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- BSTs follow the binary tree definition, with an additional property:
 - For every node, all values in the left subtree are less than that node
 - For every node, all values in the right subtree are greater than that node
- Visually, values are increasing moving from left to right – there aren't direct left-to-right connections to move in the actual structure
- Values are unique in our version (though that is not part of the definition)

Example BST

Binary Search Trees

Binary Search Trees

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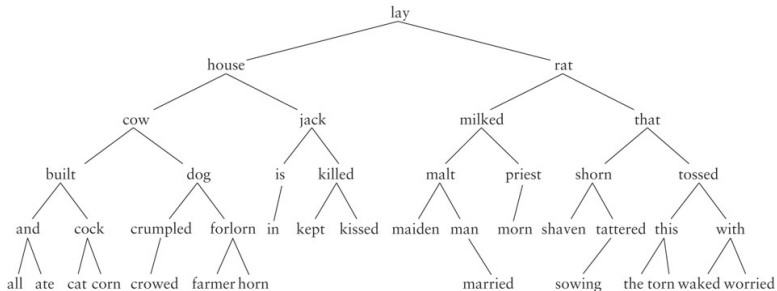
UML Diagram

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Priority Queues



Binary search tree with Strings – order is decided alphabetically

Binary Search Algorithm

Binary Search Trees

Binary Search Trees

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Priority Queues

Starting at a tree's root, this algorithm recursively searches in a tree for a target:

SEARCH(tree, target)

- 1: **if** tree is empty **then**
 - 2: **return** null // target not found
 - 3: **else if** target matches root of tree **then**
 - 4: **return** root node
 - 5: **else if** target < root node **then**
 - 6: **return** SEARCH(root's left child, target)
 - 7: **else**
 - 8: **return** SEARCH(root's right child, target)
-

Example Search Path

Binary Search Trees

Binary Search Trees

Example

Searching

Search Example

Interface

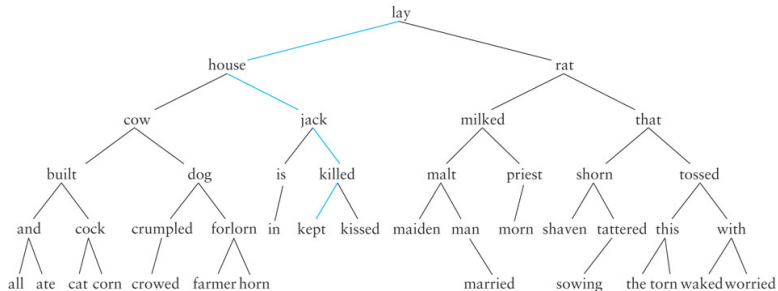
UML Diagram

find()

add()

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Priority Queues



Path to find “kept” – we only need to follow the highlighted connections

Interface

Binary Search Trees

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Method	Behavior
<code>boolean add(E item)</code>	Inserts <code>item</code> where it belongs in the tree. Returns true if item is inserted; false if it isn't (already in tree).
<code>boolean contains(E target)</code>	Returns true if <code>target</code> is found in the tree.
<code>E find(E target)</code>	Returns a reference to the data in the node that is equal to <code>target</code> . If no such node is found, returns null .
<code>E delete(E target)</code>	Removes <code>target</code> (if found) from tree and returns it; otherwise, returns null .
<code>boolean remove(E target)</code>	Removes <code>target</code> (if found) from tree and returns true ; otherwise, returns false .

BST interface – simple and efficient operations

UML Diagram

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Binary Search Trees

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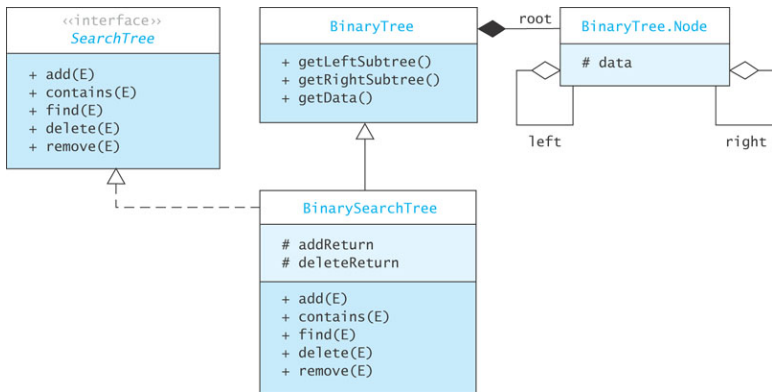


Diagram showing class models and relationships

find() implementation

Binary Search Trees

Binary Search Trees

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add()

Priority Queues

```
public E find(E target) {
    return find(root, target);
}

private E find(Node<E> localRoot, E target) {
    if (localRoot == null)
        return null;

    // Compare the target with the data at the root.
    int compResult = target.compareTo(localRoot.data);
    if (compResult == 0)
        return localRoot.data;
    else if (compResult < 0) {
        return find(localRoot.left, target);
    }
    else
        return find(localRoot.right, target);
}
```

add Algorithm

Binary Search Trees

Binary Search Trees

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add()

Priority Queues

ADD(tree, item)

- 1: **if** tree is empty **then**
 - 2: replace null with item node
 - 3: **return** true
 - 4: **else if** item matches root of tree **then**
 - 5: **return** false
 - 6: **else if** item < root node **then**
 - 7: **return** ADD(root's left child, item)
 - 8: **else**
 - 9: **return** ADD(root's right child, item)
-

add path

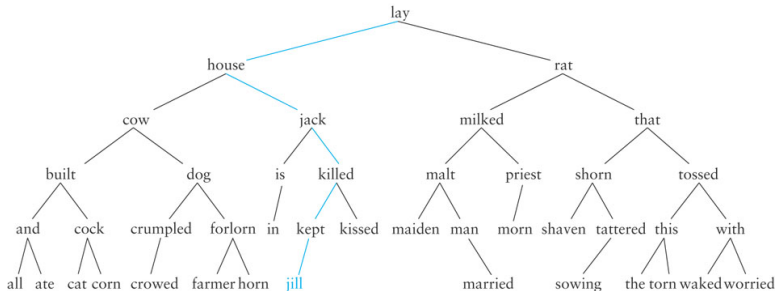
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adding “jill” in the appropriate place

add() implementation

Binary Search Trees

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Priority Queues

```
/** Starter method add.  
    pre: The object to insert must implement the  
        Comparable interface.  
    @param item The object being inserted  
    @return true if the object is inserted, false  
            if the object already exists in the tree  
*/  
public boolean add(E item) {  
    root = add(root, item);  
    return addReturn;  
}
```

add() implementation

Binary Search Trees

Binary Search Trees

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```
private Node<E> add(Node<E> localRoot, E item) {
    if (localRoot == null) {
        // item is not in the tree - insert it.
        addReturn = true;
        return new Node<E>(item);
    } else if (item.compareTo(localRoot.data) == 0) {
        addReturn = false;
        return localRoot;
    } else if (item.compareTo(localRoot.data) < 0) {
        localRoot.left = add(localRoot.left, item);
        return localRoot;
    } else {
        localRoot.right = add(localRoot.right, item);
        return localRoot;
    }
}
```



Binary Search
Trees

**Priority
Queues**

Definition

Heap

offer()

poll()

Java Class

Priority Queues

Definition

Binary Search
Trees

Priority
Queues

Definition

Heap

offer()

poll()

Java Class

- A priority queue works like a queue with an extra feature:
 - Each item in the queue can be marked with a priority
 - Smallest priority item is always at the front
- Works like a queue when all items have the same priority
- Otherwise, items in the queue might need to be rearranged when a new item is added
- Same operations as queues: offer/poll/peek

Heap

Binary Search
Trees

Priority
Queues

Definition

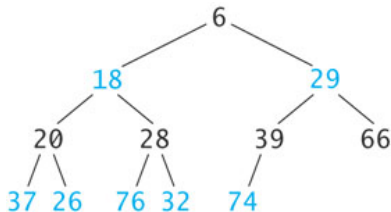
Heap

offer()

poll()

Java Class

- A **heap** is a complete binary tree with an additional property:
 - Each node in the heap is smaller than all of its descendants
- We can use a heap to efficiently implement a priority queue
- For each priority queue method that modifies the queue, we need to make sure that our heap stays consistent



offer Algorithm

Binary Search
Trees

Priority
Queues

Definition

Heap

offer()

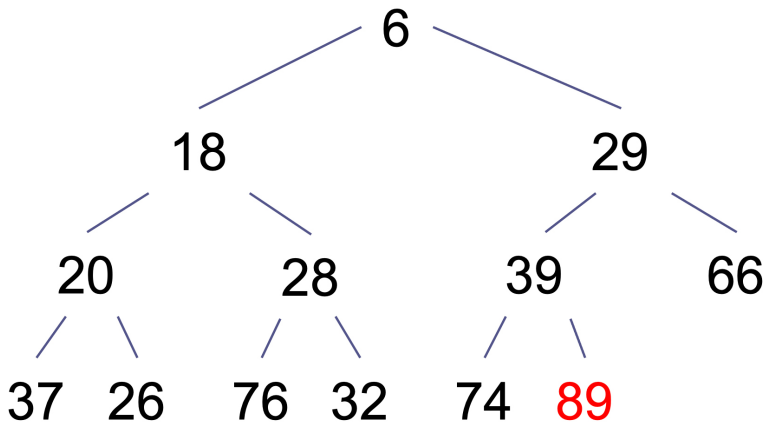
poll()

Java Class

OFFER(heap, item)

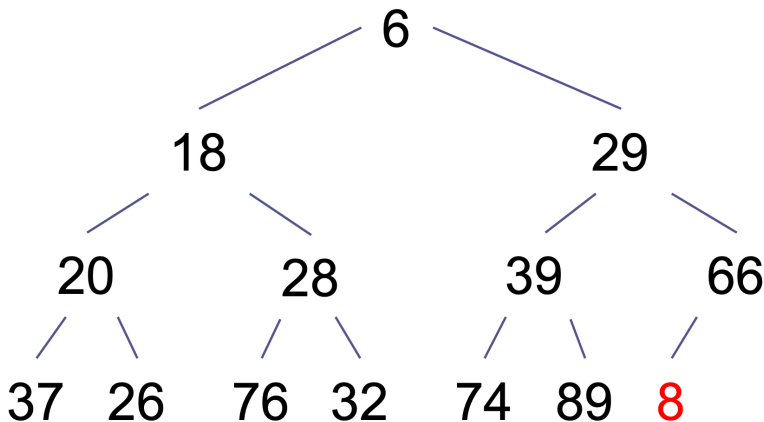
- 1: Insert new item at next position in bottom of heap
 - 2: **while** new item < parent **do**
 - 3: Swap new item and parent
-

offer example



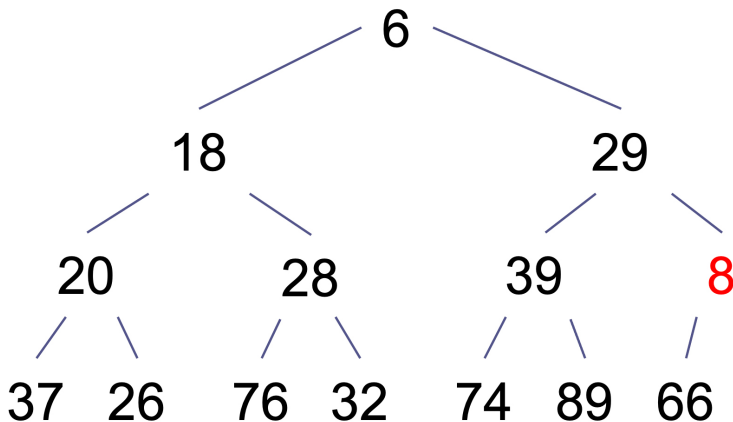
offer(89): insert at bottom, compare with 39 as parent

offer example



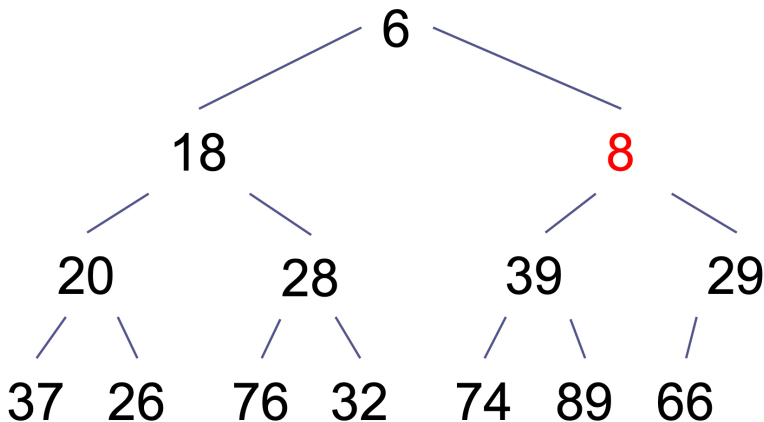
offer(8): insert at bottom, compare with 66 as parent

offer example



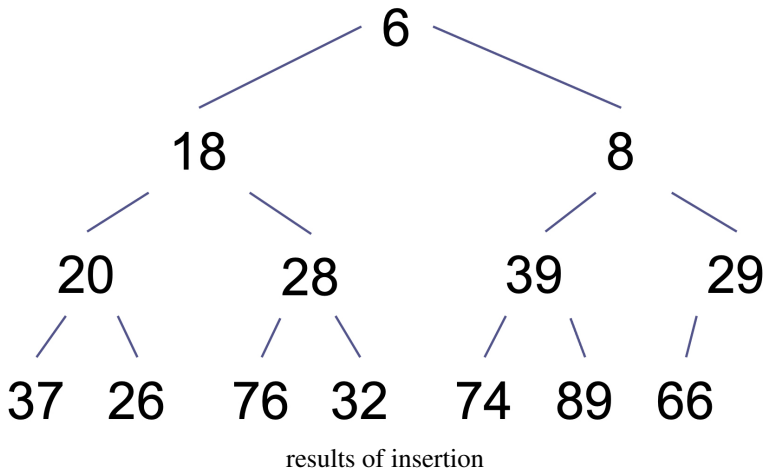
swap with parent, compare with 29 as new parent

offer example



swap with parent, compare with 6 as new parent

offer example



Binary Search
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Java Class

poll Algorithm

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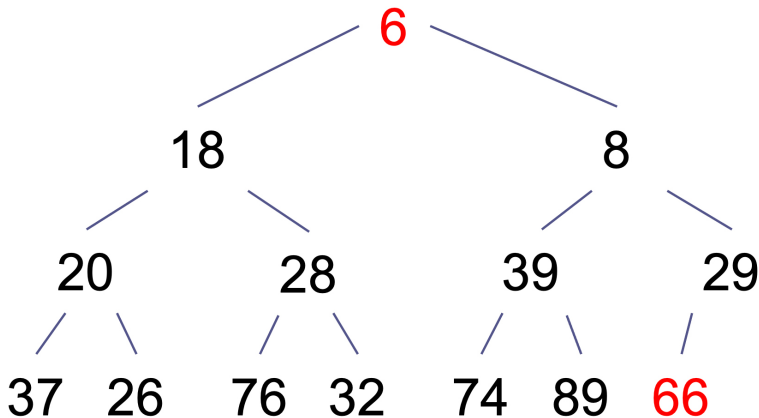
poll()

Java Class

POLL(heap)

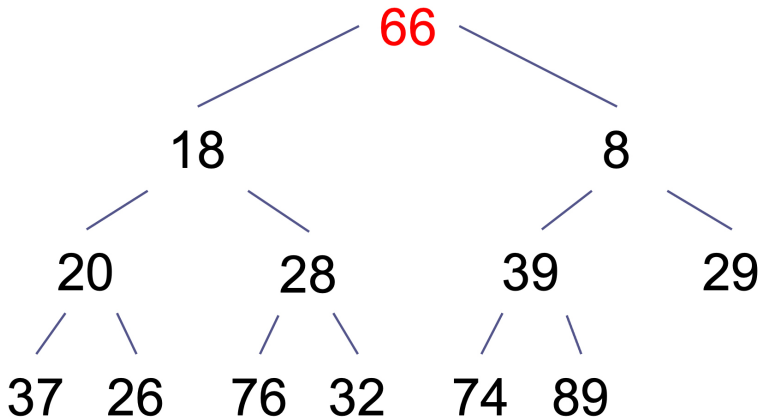
- 1: Remove root and replace it with last item in heap
 - 2: **while** moved item > valid children **do**
 - 3: Swap moved item and smallest child
 - 4: Return old root
-

poll example



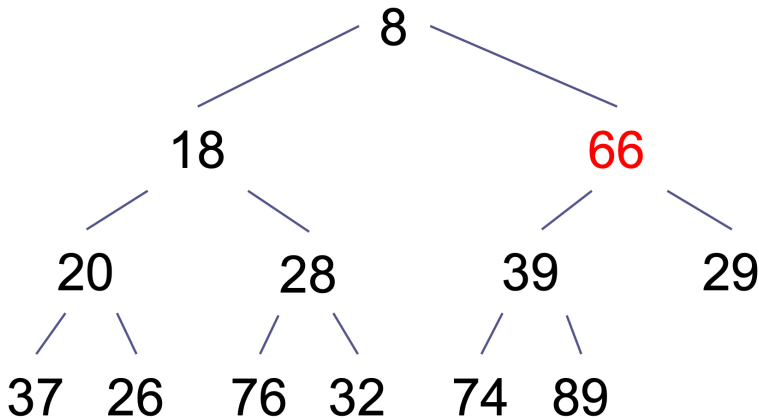
poll(): remove 6, move 66 to root location

poll example



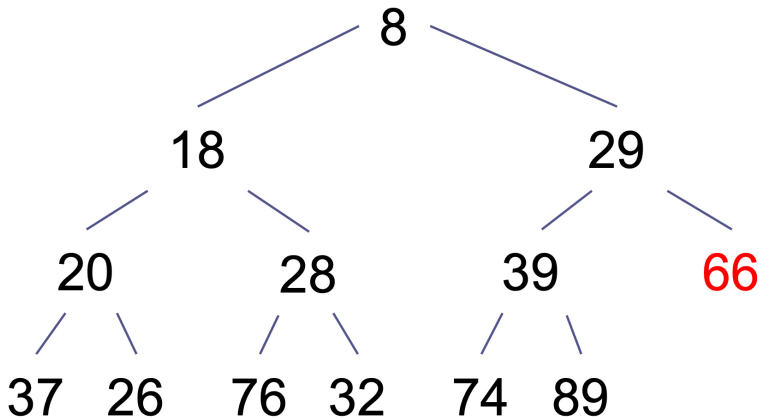
compare with children, swap with smaller child (right child)

poll example



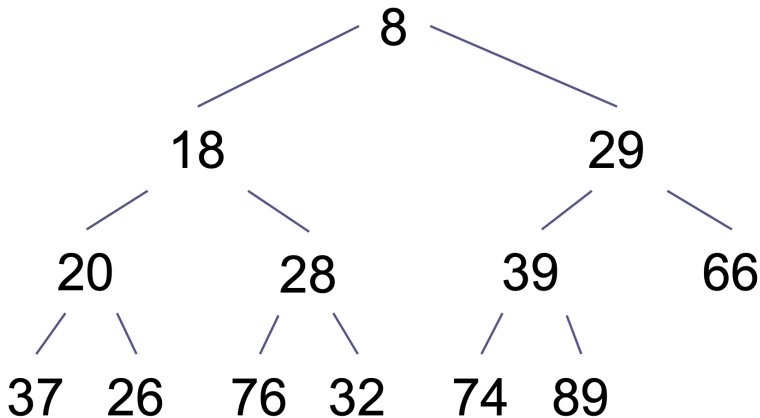
compare with children, swap with smaller child (right child)

poll example



no children to compare to, return 6 as polled value

poll example



no children to compare to, return 6 as polled value

PriorityQueue Java Class

Binary Search
Trees

Priority
Queues

Definition

Heap

offer()

poll()

Java Class

Data Field	Attribute
<code>ArrayList<E> theData</code>	An <code>ArrayList</code> to hold the data.
<code>Comparator<E> comparator</code>	An optional object that implements the <code>Comparator<E></code> interface by providing a <code>compare</code> method.
Method	Behavior
<code>KWPriorityQueue()</code>	Constructs a heap-based priority queue that uses the elements' natural ordering.
<code>KWPriorityQueue (Comparator<E> comp)</code>	Constructs a heap-based priority queue that uses the <code>compare</code> method of <code>Comparator comp</code> to determine the ordering of the elements.
<code>private int compare(E left, E right)</code>	Compares two objects and returns a negative number if object <code>left</code> is less than object <code>right</code> , zero if they are equal, and a positive number if object <code>left</code> is greater than object <code>right</code> .
<code>private void swap(int i, int j)</code>	Exchanges the object references in <code>theData</code> at indexes <code>i</code> and <code>j</code> .